



A Robotic, Dual-Sensing, Functional Optical Imaging System for Breast Cancer Detection

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ABSTRACT

Simultaneous dual-breast diffuse optical tomography (DOT) using our first-generation imager design has been shown to achieve high diagnostic sensitivity and specificity (>95%). A new DOT system has been developed that supports examination of additional features of the tumor phenotype and their interactions. Improvements include ability to accommodate a wide range of breast sizes, measures in the seated position, and application of precise actuation forces that better span variations in Young's moduli and concurrent hemodynamic response. Preliminary clinical studies document that a wealth of discriminatory features can be identified that serve to explore functional differences in the breast and surrounding host tissues.

The system is described, and preliminary experimental results from combined optical/stress-strain measurements on a healthy and tumor-bearing breast are shown.

MOTIVATION

Our strategy for increasing diagnostic power of optical breast imaging:

- Imaging of hemodynamic activity of breast vasculature during rest allows identification of tissues with deranged autoregulation (e.g., cancerous and pre-cancerous states), with high contrast [1]
- Simultaneous dual-breast imaging allows for paired comparison between diseased and healthy tissue, thus increasing statistical robustness [2,3]
- Controllable pressure maneuvers with high precision increases the normal/tumor tissue contrast based on their hemodynamic response difference.[4] This is combined with the ability to re-distribute the blood in the breast by applying fine articulation.
- The stiffness of the breast tissue can be evaluated during the pressure maneuver. This increases the ability to differentiate breast cancer based on the fact that tumor tissue is stiffer than normal tissue. [5]
- The plastic deformation is an intrinsic property of biological tissue, and the characterization of the mechanical nature of tissue may serve as a diagnostic tool for breast cancer detection. [6]

Previously described instrumentation was used for method evaluation, and demonstrated the feasibility of the first two points listed above (1 and 2). Dual-breast imaging gives a potentially high diagnostic power for many uni-variate and multivariate diagnostic metrics based on bilateral dynamic contrasts in the resting state and Valsalva maneuver.

Some practical shortcomings also became clear, which were addressed in the new imager design:

- Patients were required to lie prone, which for many was uncomfortable, and which interfered with the proper performance of provocation protocols.
- fixed-spase plastic casts as fiber-optic interface:
 - limited anatomical adaptability: good optical contact could be achieved only for a subset of breast sizes and shapes;
 - circular cross-section maximizes measuring distances in the coronal plane, thus decreasing the achievable signal-to-noise ratio.
- Fairly sparse optode arrangement of 31 sources (S) & 31 detectors (D) per breast. Rigid dual-cup probe holder accommodated only limited breast sizes, or only a portion of the breast.

To alleviate these shortcomings, the new instrument was designed with the following features:

- Cart-based design and probe holders on two articulated arms, for independent positioning of the fibers on each breast, to allow imaging the subject in a comfortable sitting position.
- Increased no. of channels: 32S x 64D per breast. (total of 2 x 2048 Ch. x 2 Wavelengths @ 1.8Hz)
- Measuring head design: clamshell mechanism
 - allows mild compression for better transmission
 - accommodates large range of breast sizes
 - allows pressure modulation
 - high spatial sensing density
- Integrated strain gauges measure pressure reaction of tissue.
- Built-in stepper motors apply pressure maneuver with high precision.

INSTRUMENTATION

The instrument design (see Fig. 1) expands on proven technology described before [7]:

- **Detection:** 2x 64-channel detector modules with Si photodiodes, adaptive gain switching, and analog lock-in amplification for demodulation of two frequency-encoded wavelengths. Signal sampling by a 4, 64-analog-channel data acquisition boards (National Instruments PCI 6033).
- **Probe holders (measuring head):** A Clamshell design comprising mechanical fingers to engage optodes in linear arrays of four (Fig. 1c) on the superior breast surface. The lower half of the clamshell rests on the superior breast surface. The upper half contains two sets of strain gauges and actuators within 1 cm of the chest wall. Vertical distance between top and bottom fingers is variable, via a single adjustment screw, to accommodate different breast sizes. The upper half of the clamshell is formed by 8 castellated metal rods (Fig 1b) which can be adjusted to accommodate different breast sizes and to apply a controlled pressure to the tissue.
- **Strain gauges:** A commercial strain gauge (SS-090-060-500P) by Micron Instruments, Inc., CA) are incorporated into each measuring head to monitor pressure exerted onto the breast tissue by sensing minute bending in the support rods, causing changes in resistance (Fig 1d). Gauge resistance changes linearly with the force applied to the rod (57 kΩ), linearly heating less than 1% over a range of 15N, see Fig 1e). Nominal resting resistance of the devices: 540 Ω at 25.5°C; load-free mounted resistance: 540 Ω at 40.0 °C. Individual strain gauge signals from all 16 channels are read out with a voltage divider and sampled by a data acquisition board (USB 6218 by National Instruments Corp., TX). Achievable measurement sensitivity is 16 mN.
- **Linear stepper motor:** The two measuring heads of the breast imager are powered by sixteen linear stepper motors (A32BL1-0020-B by Portescap Inc., TX), so that each finger can be moved forward or backward to deform the breast with high accuracy (~1mm) and over a wide range (90 mm). By moving the fingers toward the breast, a maximum force up to 17 N can be applied. Sixteen dual-full bridge drivers designed to accept standard TTL logic levels from a host computer are used for control movement and speed of the stepper motors through a USB data acquisition card (PCI-6118) from National Instruments, TX. A high speed closed-loop feedback (25 cycles per second), written in LabView software, between the strain gauge output and the stepper motor drivers allow changing of applied force to the surface of the breast with a maximum rate 1.8 N/sec.

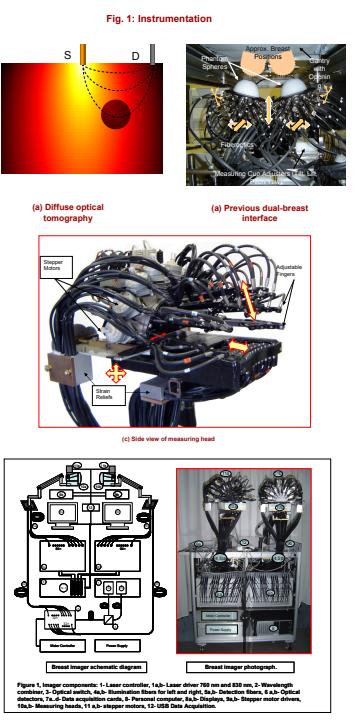


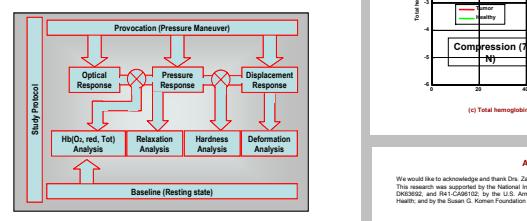
Figure 1. Imager components: 1-Laser controller, 1a-Laser driver 780 nm and 830 nm, 2-Wavelength shifter, 3-Optical fiber, 4-Optical source, 5-Optical detector, 6-Optical fiber, 7-Optical detector, 8-Optical fiber, 9-Optical detector, 10-Data acquisition card, 11-Personal computer, 12a-Displays, 13a-Stepper motor drivers, 13b-Moving heads, 14a-Stepper motors, 15a-USB Data Acquisition.

(d) Breast imager schematic diagram (e) Breast imager photograph.

Table 1: Breast imager performance and specification

Type	Parameter	Value
Optical	Wavelengths	780 nm and 830 nm
	Number of Sources	64 (32 left and 32 right)
	Number of detectors	128 (64 left and 64 right)
	Detector Sensitivity	10 pW
	Dynamic range	1:10 ⁶ (180 dB)
	Cross-talk (D-MUX)	< 1:10 ⁻⁵
	Cross-talk (detector channel)	< 1:10 ⁻⁴
Data acquisition rate	1.8 Hz x 912 channels	
Mechanical	Pressure sensitivity	0.04 N (0.01 lb)
	Capacity	15 N (3.4 lb)
	Cross-talk	1: 10 ⁻³
	Repeatability (Std. Dev.)	0.08 N (0.02 lb)
	Fingers movement range	90 mm
	Data acquisition rate	25 Hz x 16 channels

Fig. 2 Schematic of physical measurements with the breast imager and their interpretation



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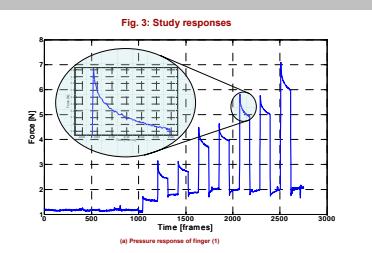


Fig. 3: Study responses

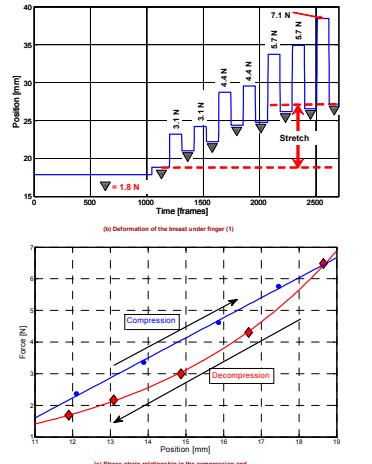


Fig. 4: Schematic of different classes of responses

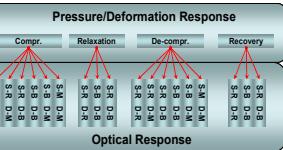


Fig. 5: Stretch Response.

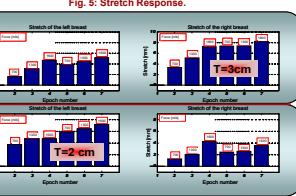


Fig. 6: Hardness (Stiffness) results.

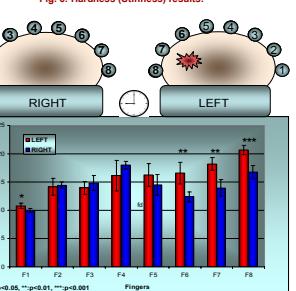


Fig. 7: Finite Element Mesh for image reconstruction

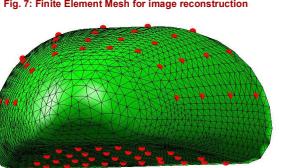


Fig. 8: 1st derivative response of Hbtot to applied pressure.

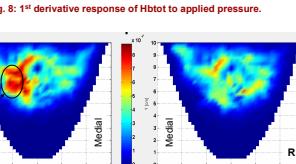


Fig. 9: Example of Image Recovery from Dynamic Phantom

METHODS

- The study protocol got approved by the Institutional Review Board at State University of New York Downstate Medical Center (protocol # 04-216).
- Measurements were performed in the seated position. Each measuring head was adjusted to make comfortable contact with the breast. Following gross adjustments, fine adjustments in optode position were made under feedback control to a fixed applied pressure (usually 400 mbars).
- After applying initial pressure (~0.4 lb / 1.8 N), collection of optical data started with a resting-state measurement lasting approximately 10 minutes.
- A sequence of external pressure changes, of varying magnitudes (max 1.6 lb / 7 N) and 60-second duration, interspersed with 60-second resting intervals, are applied to both breasts simultaneously while the optical data is being collected (Fig 3).
- The study usually takes about 50 minutes and all the optical, pressure, and deformation are stored.
- Two host computers are used to control the breast imager using LabView software, one for optical signal collection and the other to record the movement of the fingers and their pressure reading.
- The applied pressure, the position of the fingers, and all the optical signal levels are displayed on real time on the screen.

RESULTS

By deforming the breast to provoke the hemodynamic changes in the breast, six classes of the optical response occur simultaneously. Some of them are pure hemodynamic response and the others are dominated by a change in the path length between the source-detector pairs (Fig 4).

- A temporary plastic deformation of the breast is seen to occur in response to application of several external pressure pulses causing the breast not to return to its original shape. Tumor bearing breasts consistently exhibit a greater plastic deformation than normal breast under the same conditions (Fig 5).
- Estimates of tissue stiffness are determined from the 1st derivative of the strain-stress response. Fig 6 shows that the finger closer to the tumor senses a stiffer response than those at greater distances from the tumor.
- A Finite Element Mesh (FEM) corresponding to the shape of a supported breast was developed for image reconstruction (Fig 7).
- Optical data is preprocessed (normalized and filtered), and using the normalized difference method, 3D images of oxy-, deoxy-, and total hemoglobin are generated.
- Measures of amplitude and its variability across the temporal and spatial dimensions are used to diagnose presence of tumors based on the imbalance of its oxygen demand and supply [8].
- The slope of the hemodynamic response (e.g. Hb-total) in the compression phase is also used for tumor detection based on their sluggish hemodynamic response to compression (larger slope) (Fig 8).
- Phantom measurements demonstrate (1) accurate inclusion localization and (2) highly linear relation between programmed and reconstructed inclusion density. [9] Fig 9 shows a 3D image obtained from an experiment on the breast phantom.

SUMMARY

- The described breast imager is capable to sense physiological changes in the breast cancer from three independent physical measurements, optical (hemodynamic), deformation, and elasticity.
- Monitoring the hemodynamic response of the breast in compression, relaxation, decompression, and recovery phases provides many uni-variate and multivariate diagnostic metrics based on bilateral dynamic contrasts in the compression phases.
- The tumor bearing breast is stiffer than the unaffected contralateral breast, and the breast imager is able to evaluate this difference in stiffness.
- The breast responds with a temporarily plastic deformation when several epochs of compression are applied within short period of time (~10min), and this plasticity increase when in the presence of tumor.
- Phantom studies support the ability of the breast imager to localize any hemodynamic response in the breast.

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